

Strategies for Effective Offloading in GROMACS

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SC15 MIC Tuning BoF

Offloading Overview

- **GROMACS** Molecular Dynamics
- Developed with Eclipse PTP Synchronized Projects (full disclosure: I am a developer for PTP)
- Overall Strategy
 - Offload nonbonded-force calculations roughly 30-40% of compute time
 - Asynchronously run bonded-force calculations on host
- Challenge Minimize Offload Overhead
 - Minimize amount of data transfer and number of transfers
 - Minimize memory allocation and management
 - Avoid heavy use of hidden offload mappings



Minimizing Data Transfer

- Serialize data avoid multiple transfers even in same offload
- Minimize amount of data transferred
- 3 types of data
 - Volatile: Update every offload
 - Periodic: Update occasionally
 - Constant: Never update

Data Type	Size	Offload Overhead Time
Volatile	382 KB	4.28 ms
Periodic (every 5th time step)	4.80 MB	8.02 ms

Minimizing Memory Overhead

Allocations on coprocessor can degrade performance

- Avoid allocating during offload
- Allocate buffers separately and only once if possible
- Avoid using hidden offload table for memory mappings

Mysterious slowdowns occurred when using offload tables

- Failure Case 1: Automatically mirror all (most) allocations
- Failure Case 2: Allocate a new buffer prior to offload
- Failure Case 3: Use internal mapping instead of pre-allocate option

Failure case 2 is root cause?

Data Type	Reuse Buffer Overhead Time	New Buffer Overhead Time
Volatile	4.28 ms	9.71 ms
Periodic (every 5th time step)	8.02 ms	16.32 ms



Final Offload Pragma

```
#pragma offload target(mic:0) \
nocopy(nbl_lists) \
nocopy(nbl_buffer) \
nocopy(ci_buffer) \
nocopy(sci buffer) \
nocopy(cj_buffer) \
nocopy(cj4 buffer) \
nocopy(type buffer) \
nocopy(lj_comb_buffer) \
nocopy(q buffer) \
nocopy(phi_buffer_sizes) \
in (cpu_out_packet[0:packet_in_size] : into(phi_in_packet[0:packet_in_size]) REUSE targetptr) \
out(phi_out_packet[0:packet_out_size] : into(cpu_in_packet[0:packet_out_size]) REUSE targetptr) \
signal(&off signal)
```



Insights

- Benchmarking is essential
- Code design is key
 - Large data structures were the biggest problem
 - Other problem was built-in assumptions about architecture
 - Minimize disruption by separating out offload code
 - Suggestion: Design with coprocessor interface and multiple architectures in mind

Recommendations

- Benchmarking is essential. GROMACS has built-in timing library so it is easy to measure sections of code
- Simplify avoid heavy use of offload API
- More transparency needed for offload API

Remaining problems and current work

- Offload overhead still a bit high
- Work balancing can be improved
- Extending to multiple coprocessors



